

EMF 2005

REVISION LECTURES

These notes will be handed out at the revision lectures for EMF. They summarise the principal topics and the most important equations met during the course. They should be regarded only as an aid to revision and **NOT** as a complete condensation of the course material.

GENERAL ADVICE

1. **REMEMBER** and **UNDERSTAND** the **PHYSICAL MEANINGS** of the essential principles. For all of the fundamental relationships you should be able to **STATE** the law by writing the **EQUATION**, to define all the symbols and to **EXPLAIN** what the equation means using **WORDS** and **DIAGRAM(S)**.
2. Learn the **METHODS** by which the fundamental principles are applied to solve problems:
 - **Regard the problems done in the lectures, exercise classes and assignments as EXAMPLES of how to apply the basic laws. Try to see how the METHOD is always the same even for problems which look different in their details.**

e.g., All the examples we did using Gauss's Law are really the same.

All the examples we did using Ampere's Law are really the same.

etc.
3. The examination will test your knowledge and understanding of the basic ideas and also your ability to **APPLY** them to problems similar to those met during the course. The algebra will not be very complicated.

4. The last section of the course (electromagnetic waves) will not come up in the examination, but it's well worth going over it as it is excellent revision of Ampere's and Faraday's Laws).
5. When answering exam questions, try to be clear about what you are doing. The ideal answer is a mixture of **EQUATIONS, WORDS and DIAGRAM(S).**
6. Draw and clearly label **DIAGRAM(S)** when doing questions:
 - (i) it helps you to visualise the problem and keeps you on the right track in finding the solution;
 - (ii) it proves to the marker that you know what you are doing.
7. When necessary, think in **THREE DIMENSIONS**, and be prepared to shift your spatial point of view if needed.
8. Remember the laws of **VECTOR ALGEBRA**, especially the **DOT** and **CROSS** products.
9. Distinguish between vector and scalar quantities (standard method = put a bar over a vector).
10. Don't rely on these notes or any photocopied handouts for final revision - if it's not in your own handwriting you probably won't be able to remember it.

IMPORTANT CHANGES TO THE 2005 EXAM STRUCTURE !

This year, in line with many other physics exams, there will be a **COMPULSORY** section A in the paper, comprised of shorter questions on a range of topics listed in the 'AIMS AND OBJECTIVES' document which can be found on the course Homepage. Further section(s) in the paper will consist of longer questions with a choice.

VECTORS AND SCALARS

Scalar: Magnitude only

Vector: Magnitude and direction

Examples of scalars

Electric flux	ϕ
Magnetic flux	Ψ
Electric potential	V
Capacitance	C
Inductance	L
Dot product	$\bar{A} \cdot \bar{B}$

Examples of vectors

Force	\bar{F}
Velocity	\bar{v}
Electric field	\bar{E}
Magnetic field	\bar{B}
Dipole moment	\bar{P} or $\bar{\mu}$
Cross product	$\bar{A} \times \bar{B}$

VECTOR NOTATION

Written notes : **If it is a vector, put a bar over it**

Printed material : Boldface letters are usually used for vectors

Note: In this handout, bars will be used to denote vectors as a reminder that this is what you must do in written work (e.g., the exam.)

Unit vector: Magnitude = 1 Symbolised by $\hat{}$

Orthogonal unit vectors \hat{i} , \hat{j} , \hat{k} point along the three axes.

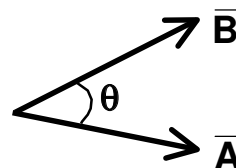
VECTOR ADDITION

- (i) Parallelogram law
- (ii) Decompose vectors into their x, y, z components
- (iii) Do NOT add vectors as scalars

VECTOR MULTIPLICATION

(i) By a scalar: $n\bar{A}$ has magnitude = nA
direction = same as that of \bar{A}

(ii) **DOT Product:** $\bar{A} \cdot \bar{B}$ is a SCALAR



$$\bar{\mathbf{A}} \cdot \bar{\mathbf{B}} = AB \cos \theta$$

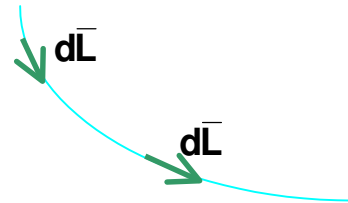
(iii) **CROSS Product:** $\bar{\mathbf{A}} \times \bar{\mathbf{B}}$ is a VECTOR

$$\text{Magnitude: } |\bar{\mathbf{A}} \times \bar{\mathbf{B}}| = AB \sin \theta$$

Direction: Perpendicular to $\bar{\mathbf{A}}$ and $\bar{\mathbf{B}}$
given by the Right Hand Rule

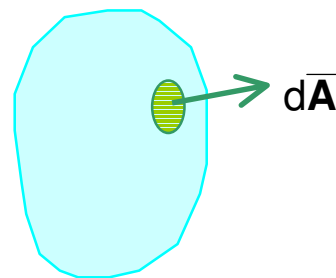
LINE AND SURFACE ELEMENT VECTORS

(i) Any path can be divided into many small LINE ELEMENTS



At any point, $d\bar{\mathbf{L}}$ has Magnitude = length dL
Direction tangential to the path

(ii) Any surface can be divided into many small SURFACE ELEMENTS



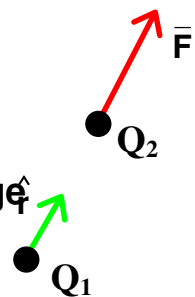
For any small patch of area ds , the NORMAL VECTOR is $d\bar{\mathbf{A}}$

$d\bar{\mathbf{A}}$ has magnitude = area dA
direction perpendicular to ds pointing outwards

THE ELECTRIC FORCE $\bar{\mathbf{F}} = \frac{Q_1 Q_2}{4\pi\epsilon_0 r^2} \hat{\mathbf{r}}$ Coulomb's Law

THE ELECTRIC FIELD $\bar{\mathbf{E}} = \frac{\bar{\mathbf{F}}}{Q}$ Force per unit charge

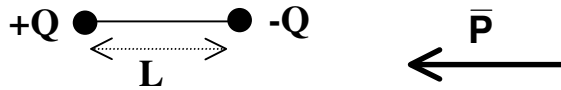
$\bar{\mathbf{E}} = \frac{Q}{4\pi\epsilon_0 r^2}$ at distance r from a point charge Q



PRINCIPLE OF SUPERPOSITION Electric fields and forces add as vectors

Examples: - Two-dimensional examples involving point charges in the x-y plane

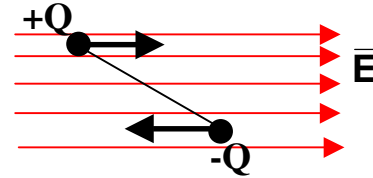
- **Field on the axis of a line of charge**

ELECTRIC DIPOLE

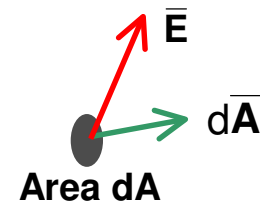
Dipole moment vector: \bar{P} has

Magnitude = QL
Direction from $-Q$ to $+Q$

Torque on a dipole due to \bar{E} is $\bar{P} \times \bar{E}$

ELECTRIC FLUX

Flux through small flat area ds is $d\phi = \bar{E} \cdot d\bar{A}$



i.e., Flux \equiv (Field)(Area)

GAUSS'S LAW

Using Coulomb's Law and the concept of electric flux, we derived Gauss's Law

$$\Phi = \oint \bar{E} \cdot d\bar{A} = \frac{Q_{\text{enc}}}{\epsilon_0}$$

Know also how to

- express it in words
- explain its physical meaning
- apply it to solve problems

Using Gauss's Law:

When? When you are given some distribution of charge and you need to find the electric field.

How?

1. Draw a diagram showing the electric field pattern
2. Choose the best Gaussian surface to make the integral easy:

i.e., make \bar{E} and $d\bar{s}$ either parallel or perpendicular

3. Work out $\Phi = \oint \bar{E} \cdot d\bar{A}$

4. Decide how much charge, Q_{enc} , is *inside* the Gaussian surface.

5. Set $\Phi = Q_{\text{enc}}/\epsilon_0$ and rearrange to find E .

Examples: Point charge, line of charge, plane of charge, sphere of charge, etc.

Gaussian surface is usually either a cylinder or a sphere. Questions often have a number of parts (e.g., find E at different radii): in these cases, the surface integral is usually of the same form but the enclosed charge may be different for the different regions.

Spherical symmetry $\Rightarrow \bar{E}$ at any point is due only to the charge inside its radius, and is the same as if all that charge were concentrated at the centre [easily proved using Gauss's Law].

CONDUCTORS IN ELECTRIC FIELDS

Electrostatic equilibrium $\Rightarrow \bar{E} = 0$ inside a perfect conductor

\bar{E} is perpendicular to the surface of a perfect conductor

Gauss's Law \Rightarrow All excess charge lies at the surface of a perfect conductor

ELECTRIC POTENTIAL, V

V at a point = PE which a charge Q *would* have at that point divided by Q .

i.e., $V = U/Q \equiv$ PE per unit charge SI units: Volts

Relationship between \bar{E} and V :

Potential difference is the line integral of the electric field

$$V_a - V_b = - \int_a^b \bar{E} \cdot d\bar{L}$$

Electric field \equiv Potential gradient

$$\bar{E} = - \left[\frac{\partial V}{\partial x} \hat{i} + \frac{\partial V}{\partial y} \hat{j} + \frac{\partial V}{\partial z} \hat{k} \right] = - \nabla V$$

Zero of potential: Defined arbitrarily - often at infinity or at the surface of a conductor.

THE ELECTRIC FIELD IS CONSERVATIVE

The work done in moving a charge is independent of the path taken: $\oint \vec{E} \cdot d\vec{L} = 0$

$\Rightarrow \vec{E}$ is zero inside a closed empty cavity in a perfect conductor

ELECTRIC POTENTIAL ENERGY CALCULATIONS

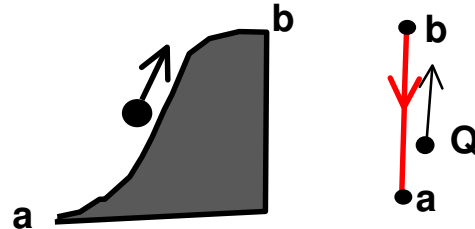
Method 1: Integrate the electric field

1. Find \vec{E} if it is not given (e.g., use Gauss's Law)
2. Choose the position of zero V (if it is not given)

3. Put $|\Delta V| = \left| \int_a^b \vec{E} \cdot d\vec{L} \right|$ Forget about the sign: just find the magnitude of ΔV

4. Use common sense and the definition of V to determine the sign of ΔV :

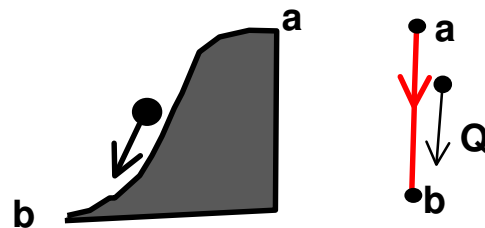
If you would need to PUSH a positive charge against \vec{E} to go from a to b then



$$V_b > V_a$$

Analogy: pushing a ball uphill

If a positive charge would be pulled by \vec{E} from P_1 to P_2 then



$$V_a > V_b$$

Analogy: A ball rolling downhill

Examples: V at distance r from a point charge $V = \frac{Q}{4\pi\epsilon_0 r}$

ΔV due to a plane of charge (close analogy with a uniform gravitational field)

ΔV due to a long cylinder of charge

Method 2: Use the principle of superposition

1. Divide the charge distribution into many small elements.
2. Regard each element as a point charge and find its contribution to the potential using $V = \frac{Q}{4\pi\epsilon_0 r}$.
3. Integrate over the whole charge distribution to find the total potential.

EQUIPOTENTIAL SURFACE V is the same everywhere

$\Rightarrow \vec{E}$ points perpendicular to an equipotential surface (e.g., the surface of a conductor).

ELECTRIC ENERGY

For a system of n point charges $U_{\text{tot}} = \frac{1}{2} \sum_{i=1}^n Q_i V_i$

where $V_i =$ potential at the position of charge Q_i due to the combined effects of all the other charges.

Energy of a charged conductor: $U = \frac{1}{2} QV$

- Examples:
- Conducting sphere
 - Parallel plate capacitor
 - Etc.

ENERGY DENSITY OF THE ELECTRIC FIELD $u = \frac{1}{2} \epsilon_0 E^2$

CAPACITANCE, C In general $V \propto Q$ $C = Q/V$

\Rightarrow Energy of a charged conductor is $U = \frac{1}{2} CV^2 = \frac{1}{2} \frac{Q^2}{C}$

Finding C:

1. Imagine $\pm Q$ placed on conductors.
2. Find \bar{E} (e.g., use Gauss's Law).
3. Find $|\Delta V|$ (never mind the sign).
4. Put $C = Q/V$
 - Q cancels out
 - C depends only on the size, shape, separation of the conductors

Examples: - Conducting sphere - Parallel plate capacitor
 - Spherical capacitor - Cylindrical capacitor

Capacitors in parallel: $C_{\text{tot}} = C_1 + C_2$ (V is same for both)

Capacitors in series : $\frac{1}{C_{\text{tot}}} = \frac{1}{C_1} + \frac{1}{C_2}$ (Q is same for both)

DIELECTRICS AND POLARISATION This equation defines the **DIELECTRIC CONSTANT**

$$\bar{E}_{\text{tot}} = \bar{E}_o - \bar{E}_p = \frac{\bar{E}_o}{K} \quad K (\geq 1)$$

When the medium is not a vacuum, simply replace ϵ_0 with $\kappa\epsilon_0$.

ELECTRIC CURRENT $I = dQ/dt$ $I \propto E \Rightarrow I \propto \Delta V$

Resistivity and resistance: $R = \rho \frac{L}{A}$ L = length; A = Area

Ohm's Law: $I = \frac{\Delta V}{R}$

ELECTROMOTIVE FORCE, \square

\square = PE gained by one Coulomb of charge in passing through source of emf (analogy of water pump working in the Earth's gravitational field)

\square = U/Q Energy per unit charge
 \Rightarrow Units are same as Potential, Volts

Note: emf is **NOT** a force

ELECTRIC POWER $P = \frac{dU}{dt} = \square = \square I$

Power dissipated (as heat) in a resistor $P = I^2 R = V^2/R$

KIRCHHOFF'S LAWS

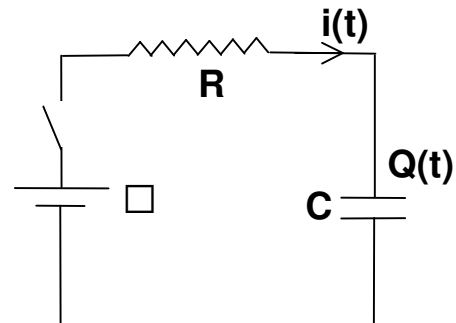
Voltage Law: For any closed loop in a circuit, the sum of all emfs and potential drops is zero.

Current Law: The sum of all currents flowing into a node is zero.

STEP RESPONSE OF THE RC CIRCUIT

(Example of a first-order linear system)

Switch closed at $t = 0$
 Capacitor charges up

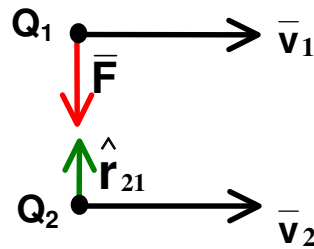


1. Use KVL to derive differential equation for Q .
2. Separate variables, Q on left, t on right
3. Integrate and use initial conditions to find constant of integration \rightarrow find $Q(t)$.

THE MAGNETIC FORCE

Caused by charges in MOTION (i.e., currents)

$$\vec{F} = \frac{\mu_0 Q_1 Q_2}{4\pi r^2} (\vec{v}_1 \vec{v}_2) \hat{r}_{21}$$



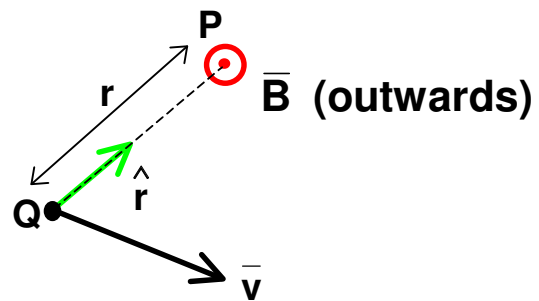
Note: Magnetic force is perpendicular to $\vec{v} \Rightarrow$ it doesn't change the speed of the particle, only its DIRECTION

THE MAGNETIC FIELD

Defined by $\vec{F} = Q(\vec{v} \times \vec{B})$

Magnetic field at P due to moving Q is

$$\vec{B} = \frac{\mu_0 Q}{4\pi r^2} (\vec{v} \times \hat{r})$$



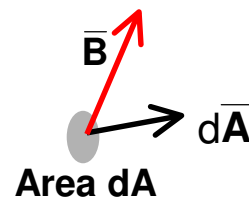
MAGNETIC FIELD LINES

Example of charge moving OUT OF PAPER \rightarrow magnetic field lines form CLOSED LOOPS

MAGNETIC FLUX

Flux through small flat area ds is $d\Psi = \vec{B} \cdot d\vec{s}$

i.e., Flux \equiv (Field)(Area)



GAUSS'S LAW FOR THE MAGNETIC FIELD $\Psi = \oint \vec{B} \cdot d\vec{A} = 0$

(Magnetic field lines form closed loops; there are no magnetic monopoles)

THE LORENTZ FORCE

If Q moves with velocity \vec{v} in an electric field \vec{E} and a magnetic field \vec{B} then force on it is

$$\vec{F} = Q[\vec{E} + (\vec{v} \times \vec{B})]$$

Examples: Velocity selector

Magnetic field only \rightarrow circular or spiral motion

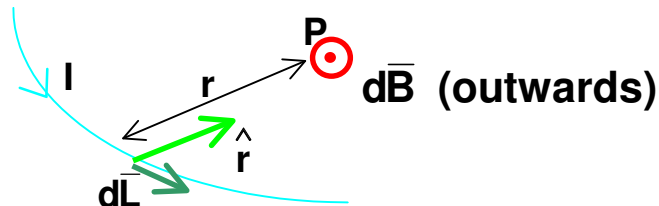
Hall effect: Conductor in magnetic field

- \rightarrow Magnetic force on charges
- \rightarrow Separation of charges
- \rightarrow Transverse electric field
(direction gives sign of carriers)
- \rightarrow ΔV across sides \propto no. density of the carriers

BIOT-SAVART LAW

Gives \vec{B} due to a CURRENT-CARRYING ELEMENT

$$d\vec{B} = \frac{\mu_0 I}{4\pi r^2} (d\vec{L} \times \hat{r})$$

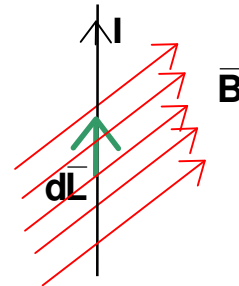


To find the total field at P, integrate over the whole length of the wire.

FORCE ON A CURRENT-CARRYING WIRE IN A MAGNETIC FIELD

$$d\vec{F} = dQ(\vec{v} \times \vec{B}) \Rightarrow d\vec{F} = I(d\vec{L} \times \vec{B})$$

If $\vec{B} \perp$ wire, then $dF = BIdL$

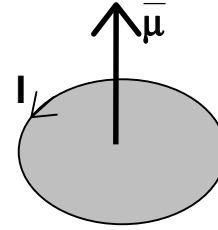


\Rightarrow Force between two parallel wires is $F = \frac{\mu_0 I_1 I_2}{2\pi r}$
(basis of the definition of the Ampere).

MAGNETIC DIPOLE (\equiv CURRENT- CARRYING LOOP)

DIPOLE MOMENT VECTOR $\vec{\mu}$

Magnitude = $nIA = (\text{No. of turns})(\text{Current})(\text{Area})$
 Direction = \perp to the plane of the loop, given by the right hand rule



TORQUE on a magnetic dipole due to external \vec{B} : $\vec{\tau} = \vec{\mu} \times \vec{B}$

RELATIVE PERMEABILITY

If the medium is not a vacuum, then replace μ_0 with $\mu_0\mu_r$

$\mu_r \approx 1$ for most materials

AMPERE'S LAW

Relates the magnetic field to the current distribution that produces it

$$\oint \vec{B} \cdot d\vec{L} = \mu_0 I_{\text{enc}}$$

Using Ampere's Law:

When? When you are given some distribution of charge and you want to find the magnetic field

- How?**
1. Draw a diagram showing the magnetic field pattern
 2. Choose an imaginary closed path to make the line integral easy
 i.e., make \vec{B} and $d\vec{L}$ either parallel or perpendicular
 View along the axis (current flowing out of the page, so that you can draw the path in the plane of the page).
 3. Work out $\oint \vec{B} \cdot d\vec{L}$
 4. Decide how much current, I_{enc} , is flowing through the loop.
 5. Equate the results of 3 and 4 and rearrange to find B .

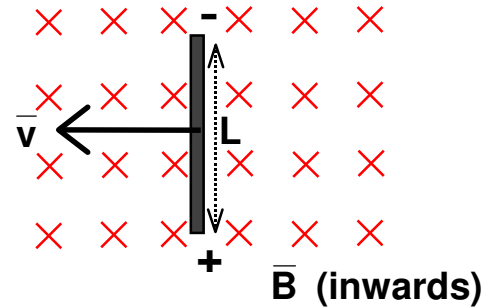
Examples:

- Long thin wire: $B = \mu_0 I / (2\pi r)$
- Long solid cylinder (similar to wire)
- Long solenoid: $B = \mu_0 nI$

ELECTROMAGNETIC INDUCTION

Changing \vec{B} \rightarrow Induced \vec{E}

Introduced through MOTIONAL emf :



$$\mathcal{E} = vBL$$

\rightarrow $\mathcal{E} =$ Rate of sweeping out of magnetic flux:

$$\mathcal{E} = - \frac{d\Psi}{dt} \quad \text{or} \quad \oint \vec{E} \cdot d\vec{L} = - \frac{d\Psi}{dt} \quad \text{FARADAY'S LAW}$$

The emf induced around a closed loop = - Rate of change of magnetic flux through the loop

Negative sign \equiv LENZ'S LAW: The induced emf OPPOSES the **CHANGE** in \vec{B} that produces it (i.e., it tries to keep \vec{B} constant).

INDUCTANCE

Changing current in one circuit

\rightarrow changing \vec{B}

\rightarrow changing Ψ

\rightarrow induced \vec{E} in another circuit (Mutual Inductance)
in the same circuit (Self Inductance)

Inductance = Flux/Current

MUTUAL INDUCTANCE

$$M = \frac{\Psi_{21}}{I_1}$$

Ψ_{21} = Flux through circuit 2
due to current I_1 in
circuit 1

$$\square_2 = -M \frac{dI_1}{dt}$$

SELF INDUCTANCE

$$L = \frac{\Psi}{I}$$

Ψ = Flux through circuit
due to its own current

$$\square = -L \frac{dI}{dt}$$

Finding M or L:

1. Assume current I flows in the circuit (L) or in one of the circuits (M)
2. Find \vec{B} (e.g., using Ampere's Law)
3. Find Ψ , the flux through the (other) circuit
4. Put L or $M = \Psi/I$. I will cancel out.
Inductance depends only on the size, shape, no. of turns, etc.

ENERGY STORAGE IN INDUCTORS

Energy stored = amount of work which must be done in order to increase the current from 0 to I against the opposing (back) emf induced by the changing current.

$$U = \frac{1}{2} LI^2$$

ENERGY DENSITY OF THE MAGNETIC FIELD

$$u = \frac{1}{2} \frac{B^2}{\mu_0} \quad [\text{SI units: J m}^{-3}]$$

(Derived using example of solenoid)

FINDING MAGNETIC ENERGY

1. Find B as a function of position
2. Hence find u
3. Define a suitable VOLUME ELEMENT and integrate $u \, d(\text{Volume})$ to find U_{tot} .

SUMMARY OF MAXWELL'S EQUATIONS (IN INTEGRAL FORM)

① $\oint \bar{\mathbf{E}} \cdot d\bar{\mathbf{A}} = \frac{Q_{\text{enclosed}}}{\epsilon_0}$ Gauss's Law for the Electric Field

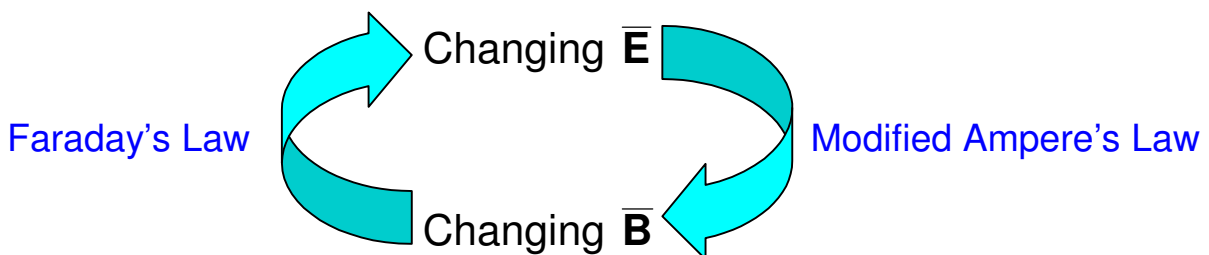
② $\oint \bar{\mathbf{B}} \cdot d\bar{\mathbf{A}} = 0$ Gauss's Law for the Magnetic Field

③ $\oint \bar{\mathbf{E}} \cdot d\bar{\mathbf{L}} = -\frac{d\Psi}{dt}$ Faraday's Law of Induction

④ $\oint \bar{\mathbf{B}} \cdot d\bar{\mathbf{L}} = \mu_0 I + \mu_0 \epsilon_0 \frac{d\Phi}{dt}$ Maxwell's modification of Ampere's Law

NB: ③ \Rightarrow Changing $\bar{\mathbf{B}}$ generates $\bar{\mathbf{E}}$

④ \Rightarrow Changing $\bar{\mathbf{E}}$ generates $\bar{\mathbf{B}}$



\Rightarrow OSCILLATION OF ENERGY BETWEEN THE ELECTRIC AND MAGNETIC FIELDS

\Rightarrow **ELECTROMAGNETIC WAVES EXIST**