

5.1) 99.73 %

5.2) $x_1 = 0.655 \pm 0.024$

$x_2 = 0.59 \pm 0.08$

$x_3 = 0.789 \pm 0.071$

$$\bar{x} = \frac{\sum_{i=1}^3 x_i / \sigma_i^2}{\sum_{i=1}^3 1/\sigma_i^2}$$

$$\sigma^2 = \sum_{i=1}^3 1/\sigma_i^2$$

as the results are ∇ uncorrelated.

x_j	0.655	0.59	0.789
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σ_j	0.024	0.08	0.071
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σ_j^2	0.000576	0.0064	0.005041
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$1/\sigma_j^2$	1736.11	156.25	198.373	$\sum 1/\sigma_i^2 = 2090.73$
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x_j/σ_j^2	1137.15	92.1875	156.516	$\sum x_i/\sigma_i^2 = 1385.86$
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$$\therefore \bar{x} = 0.663 \pm 0.022$$

5.3) $\lambda = r e^{i\phi}$

$r = 1.0 \pm 0.1$, $\phi = 0.0 \pm 0.2$ rad.

$x = r \cos \phi$

$y = r \sin \phi$

$$\sigma_x^2 = \left(\frac{\partial x}{\partial r} \right)^2 \sigma_r^2 + \left(\frac{\partial x}{\partial \phi} \right)^2 \sigma_\phi^2$$

$$= \cos^2 \phi \sigma_r^2 + r^2 \sin^2 \phi \sigma_\phi^2$$

$$= 0.01$$

$$\sigma_y^2 = \left(\frac{\partial y}{\partial r} \right)^2 \sigma_r^2 + \left(\frac{\partial y}{\partial \phi} \right)^2 \sigma_\phi^2$$

$$= \sin^2 \phi \sigma_r^2 + r^2 \cos^2 \phi \sigma_\phi^2$$

$$= 0.04$$

$\therefore \sigma_x = 0.1$ & $\sigma_y = 0.2$

$$5.4) \quad A = \frac{N_1 - N_2}{N_1 + N_2} \quad ; \quad N = N_1 + N_2$$

$$= \frac{N_1}{N} - \frac{N - N_1}{N}$$

$$= 2\epsilon - 1 \quad \text{where } \epsilon = N_1/N$$

$$\sigma_a^2 = \left(\frac{\partial A}{\partial \epsilon} \right)^2 \sigma_\epsilon^2 = 4 \sigma_\epsilon^2$$

σ_ϵ^2 is given by the binomial uncertainty $\epsilon(1-\epsilon)/N$; thus

$$\sigma_a^2 = 4 \frac{\epsilon(1-\epsilon)}{N} \Rightarrow \sigma_a = 2 \sqrt{\frac{\epsilon(1-\epsilon)}{N}}$$

$$5.5) \quad T = 1.62 \pm 0.20 \text{ s}$$

$$L = 0.646 \pm 0.005$$

what is g ?

$$g = \frac{4\pi^2 L}{T^2}$$

$$\therefore \sigma_g^2 = \left(\frac{8\pi^2 L}{T^3} \right)^2 \sigma_T^2 + \left(\frac{4\pi^2}{T^2} \right)^2 \sigma_L^2$$

$$\therefore g = 9.72 \text{ m/s}^2 \pm 2.40 \text{ m/s}^2$$

$$\therefore g = (9.7 \pm 2.4) \text{ m/s}^2$$

5.6) One would expect a factor of 10 improvement (neglecting σ_L), as $\sigma_g \propto \sigma_T$ and the uncertainty on one oscillation, when ten are measured, is $1/10^{\text{th}}$ of the uncertainty of measuring just a single oscillation.

$$5.7) \quad L = (0.646 \pm 0.005) \text{ m}$$

$$\sigma_T = 0.2 \text{ s}$$

T	1.62	1.56	1.59	1.50	1.56	1.62	1.59	1.65	1.60	1.56
g	9.718	10.480	10.088	11.335	10.480	9.718	10.088	9.368	9.962	10.479

$$\langle T \rangle = 1.585 \text{ s} \quad \sigma_T^{\text{mean}} = 0.042 \text{ s}$$

$$\langle g \rangle = 10.171 \text{ m/s}^2 \quad \sigma_g = 0.553 \text{ m/s}^2$$

5.8)

$$x_1 = 1.2 \pm 0.3$$

$$x_2 = 1.8 \pm 0.3$$

$$\bar{x} = \frac{\sum_{i=1}^2 x_i / \sigma_i^2}{\sum_{i=1}^2 1 / \sigma_i^2} + \left(\sum_{i=1}^2 1 / \sigma_i^2 \right)^{-1/2}$$

$$\therefore \sum \frac{1}{\sigma_i^2} = \frac{1}{0.09} + \frac{1}{0.09} = 22.222$$

$$\Rightarrow \sigma = 0.212$$

$$\sum x_i / \sigma_i^2 = 13.3 + 20 = 33.3$$

$$\therefore \bar{x} = 1.5 \pm 0.2$$

5.9)

$$x_1 = 1.0 \pm 0.5$$

$$x_2 = 2.0 \pm 0.5$$

$$\sum \frac{1}{\sigma_i^2} = \frac{1}{0.25} + \frac{1}{0.25} = 8 \quad \Rightarrow \sigma = 1/\sqrt{8} = 0.354 \text{ (3dp)}$$

$$\sum x_i / \sigma_i^2 = 4 + 8 = 12$$

$$\therefore \bar{x} = 1.5 \pm 0.354 \quad \text{or } \bar{x} = 1.5 \pm 0.4 \text{ (1dp)}$$

5.10)

$$Q = E(1 - 2\omega)$$

$$\sigma_Q^2 = \left(\frac{\partial Q}{\partial E} \right)^2 \sigma_E^2 + \left(\frac{\partial Q}{\partial \omega} \right)^2 \sigma_\omega^2$$

$$= (1 - 2\omega)^2 \sigma_E^2 + (-2E)^2 \sigma_\omega^2$$

$$\therefore \sigma_Q = \sqrt{(1 - 2\omega)^2 \sigma_E^2 + 4E^2 \sigma_\omega^2}$$

5.11)

Posture of student (slouching / upright)

offset from footwear

accuracy of measuring device

use of measuring device (along axis of height of student; or rotated relative to that?)

Time of day of the measurement (relative to the time the person wakes up)

as height changes depending on how long one has been lying down while asleep.

etc...

5.12)

EXPT 1:

$$A_1 = 2.0 \pm 0.2$$

$$B_1 = 0.0 \pm 0.5$$

$$e_{AB} = 0.3$$

EXPT 2:

$$A_2 = 1.5 \pm 0.5$$

$$B_2 = -1.0 \pm 0.3$$

$$e_{AB} = 0.1$$

$$\bar{x} = \left[\sum_i V_i^{-1} \right]^{-1} \left[\sum_i V_i^{-1} \cdot x_i \right]$$

$$V = \left[\sum_i V_i^{-1} \right]^{-1}$$

$$\therefore x_1 = \begin{pmatrix} 2.0 \\ 0.0 \end{pmatrix} \quad e_1 = \begin{pmatrix} 1 & 0.5 \\ 0.5 & 1 \end{pmatrix} \Rightarrow V_1 = \begin{pmatrix} 0.04 & 0.05 \\ 0.05 & 0.25 \end{pmatrix}$$

$$x_2 = \begin{pmatrix} 1.5 \\ -1.0 \end{pmatrix} \quad e_2 = \begin{pmatrix} 1 & 0.1 \\ 0.1 & 1 \end{pmatrix} \Rightarrow V_2 = \begin{pmatrix} 0.25 & 0.015 \\ 0.015 & 0.09 \end{pmatrix}$$

$$\therefore V = \begin{pmatrix} 0.0293 & 0.01299 \\ 0.01299 & 0.0662 \end{pmatrix} \quad \bar{x} = \begin{pmatrix} 1.819 \\ -0.738 \end{pmatrix}$$

$$\text{i.e. } A = 1.82 \pm 0.17$$

$$B = -0.74 \pm 0.26$$

$$e_{AB} = 0.013$$

5.13)

$$A_1 = 2.0 \pm 0.5 \quad B_1 = 0.0 \pm 0.1 \quad \cancel{e_{AB} = 0.3} \quad e_{AB} = 0.0$$

$$A_2 = 1.5 \pm 0.5 \quad \cancel{B_2 = 0.0 \pm 0.2} \quad B_2 = 0.5 \pm 0.2 \quad \cancel{e_{AB} = 0.3} \quad e_{AB} = 0.3$$

~~4 observable or 6 candidate~~

$$x_1 = \begin{pmatrix} 2.0 \\ 0.0 \end{pmatrix} \quad e_1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \Rightarrow V_1 = \begin{pmatrix} 0.25 & 0 \\ 0 & 0.01 \end{pmatrix}$$

$$x_2 = \begin{pmatrix} 1.5 \\ 0.5 \end{pmatrix} \quad e_2 = \begin{pmatrix} 1 & 0.3 \\ 0.3 & 1 \end{pmatrix} \Rightarrow V_2 = \begin{pmatrix} 0.25 & 0.03 \\ 0.03 & 0.04 \end{pmatrix}$$

$$\therefore V = \begin{pmatrix} 0.120 & 0.003 \\ 0.003 & 0.008 \end{pmatrix} \quad \bar{x} = \begin{pmatrix} 1.59 \\ 0.11 \end{pmatrix} \quad \therefore e_{AB} = 0.003$$

$$\therefore A = 1.59 \pm 0.35$$

$$B = 0.11 \pm 0.09$$

6.14

$A_1 = 3 \pm 1$

$B_1 = 0 \pm 1$

$C_1 = 0 \pm 1$

$A_2 = 2 \pm 1$

$B_2 = 1 \pm 2$

$C_2 = 1 \pm 1$

$\sigma_{ij} = 0 \quad \forall i, j \quad (i \neq j).$

$$\therefore x_1 = \begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix}$$

$$V_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$x_2 = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

$$V_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

One can follow the same procedure as the previous 2 questions or resort to the uncorrelated variant of these to compute the average values; actually as there are no correlations one can treat A, B & C as indep. problems.

$$\text{eg. A: } \sum \frac{1}{\sigma_i^2} = \frac{1}{1^2} + \frac{1}{1^2} = 2 \Rightarrow \sigma_A = 1/\sqrt{2}$$

$$\text{B: } = \frac{1}{1^2} + \frac{1}{2^2} = \frac{5}{4} \Rightarrow \sigma_B = 2/\sqrt{5}$$

etc.

$$\therefore \bar{x} = \begin{pmatrix} 2.5 \\ 0.2 \\ 0.5 \end{pmatrix} \quad \& \quad V = \begin{pmatrix} 1/2 & 0 & 0 \\ 0 & 4/5 & 0 \\ 0 & 0 & 1/2 \end{pmatrix}$$

$$\Rightarrow A = 2.5 \pm 1/\sqrt{2} = 2.5 \pm 0.7 \quad (2dp)$$

$$B = 0.2 \pm 2/\sqrt{5} = 0.2 \pm 0.9 \quad (1dp)$$

$$C = 0.5 \pm 1/\sqrt{2} = 0.5 \pm 0.7 \quad (1dp)$$

S.15)

$$E^2 = m_0^2 c^4 + p^2 c^2$$

$$\therefore m_0 = \sqrt{\frac{E^2 - p^2 c^2}{c^4}}$$

$$\frac{\delta E}{E} = 0.01$$

$$\frac{\delta p}{p} = 0.01$$

$$\delta m_0^2 = \left(\frac{\partial m_0}{\partial E} \right)^2 \delta E^2 + \left(\frac{\partial m_0}{\partial p} \right)^2 \delta p^2$$

$$\frac{\partial m_0}{\partial E} = \frac{1}{c^2} \cdot \frac{\partial}{\partial E} \left(E^2 - p^2 c^2 \right)^{1/2}$$

$$= \frac{1}{2c^2} \cdot \frac{2E}{\sqrt{E^2 - p^2 c^2}}$$

$$\therefore \left(\frac{\partial m_0}{\partial E} \right)^2 = \frac{E^2}{c^4 (E^2 - p^2 c^2)}$$

$$\frac{\partial m_0}{\partial p} = \frac{1}{c^2} \cdot \frac{\partial}{\partial p} \left(E^2 - p^2 c^2 \right)^{1/2}$$

$$= \frac{1}{2c^2} \cdot \frac{-2p^2 c^2}{\sqrt{E^2 - p^2 c^2}}$$

$$\therefore \left(\frac{\partial m_0}{\partial p} \right)^2 = \frac{p^2}{E^2 - p^2 c^2}$$

$$\therefore \delta m_0^2 = \frac{E^2 \cdot \delta E^2}{c^4 (E^2 - p^2 c^2)} + \frac{p^2 \delta p^2}{E^2 - p^2 c^2} \quad ; \text{ where } \delta E = 0.01 E$$

$$\delta p = 0.01 p$$

$$\therefore \delta m_0^2 = \frac{10^{-4}}{E^2 - p^2 c^2} \left[\frac{E^4}{c^4} + p^4 \right]$$

$$\therefore \delta m_0 = \frac{10^{-2}}{\sqrt{E^2 - p^2 c^2}} \left[\frac{E^2}{c^4} + p^4 \right]^{1/2}$$